

Numerical Methods for Partial Differential Equation.

ODE

Exercise - 2

Ans - 1

a) $\frac{d^2\theta}{dt^2} + \frac{g}{L}\theta = 0$

let $\frac{d\theta}{dt} = z$ ----- eq(1) $\theta(1) = 0.4 \text{ rad}$
 $= f_1(t, \theta, z)$

$\frac{dz}{dt} + \frac{g}{L}\theta = 0$

$\frac{dz}{dt} = -\frac{g}{L}\theta$ ----- eq(2) $z(1) = 0 \text{ rad/s}$
 $= f_2(t, \theta, z)$

2nd order Runge Kutta method

$\theta_{i+1} = \theta_i + \left(\frac{1}{2}K_1^\theta + \frac{1}{2}K_2^\theta\right)h$

$z_{i+1} = z_i + \left(\frac{1}{2}K_1^z + \frac{1}{2}K_2^z\right)h$

where,

$K_1^\theta = f_1(t_i, \theta_i, z_i)$

$K_2^\theta = f_1(t_i + h, \theta_i + K_1^\theta h, z_i + K_1^z h)$

$K_1^z = f_2(t_i, \theta_i, z_i)$

$K_2^z = f_2(t_i + h, \theta_i + K_1^\theta h, z_i + K_1^z h)$

With 2 time steps

$$i=0, h=-0.5, \theta_0=0.4, t_0=1, z_0=0 \text{ rad/s}$$

$$\begin{aligned} K_1^{\theta} &= f_1(t_0, \theta_0, z_0) \\ &= f_1(1, 0.4, 0) \\ &= 0 \end{aligned}$$

$$\begin{aligned} K_1^z &= f_2(t_0, \theta_0, z_0) \\ &= f_2(1, 0.4, 0) \\ &= -3.92 \end{aligned}$$

$$\begin{aligned} K_2^{\theta} &= f_1(t_0+h, \theta_0+K_1^{\theta}h, z_0+K_1^z h) \\ &= f_1(0.5, 0.4, 1.96) \\ &= 1.96 \end{aligned}$$

$$\begin{aligned} K_2^z &= f_2(t_0+h, \theta_0+K_1^{\theta}h, z_0+K_1^z h) \\ &= f_2(0.5, 0.4, 1.96) \\ &= -3.92 \end{aligned}$$

$$\begin{aligned} \therefore \theta_1 &= \theta_0 + \left(\frac{1}{2}K_1^{\theta} + \frac{1}{2}K_2^{\theta} \right) h \\ &= 0.4 + \left(\frac{1}{2} \times 0 + \frac{1}{2} \times 1.96 \right) \times 0.5 \\ &= -0.09 \text{ rad} \end{aligned}$$

$$\begin{aligned} z_1 &= z_0 + \left(\frac{1}{2}K_1^z + \frac{1}{2}K_2^z \right) h \\ &= 0 + \left(\frac{1}{2} \times -3.92 + \frac{1}{2} \times -3.92 \right) \times -0.5 \\ &= -1.96 \end{aligned}$$

When,

$$i=1, \quad t_1=0.5, \quad h=-0.5, \quad \theta_1=-0.09, \quad z_1=1.96$$

$$K_1^\theta = f_1(t_1, \theta_1, z_1)$$

$$= f_1(0.5, -0.09, 1.96)$$

$$= 1.96$$

$$K_1^z = f_2(t_1, \theta_1, z_1)$$

$$= f_2(0.5, -0.09, 1.96)$$

$$= 0.882$$

$$K_2^\theta = f_1(t_1+h, \theta_1+K_1^\theta h, z_1+K_1^z h)$$

$$= f_1(0, -1.97, 1.519)$$

$$= 1.519$$

$$K_2^z = f_2(t_1+h, \theta_1+K_1^\theta h, z_1+K_1^z h)$$

$$= f_2(0, -1.97, 1.519)$$

$$= 19.306$$

$$\theta_2 = \theta_1 + \left(\frac{1}{2} K_1^\theta + \frac{1}{2} K_2^\theta \right) h$$

$$= -0.09 + \left(\frac{1}{2} \times 1.96 + \frac{1}{2} \times 1.519 \right) \times -0.5$$

$$= -0.95975$$

With 4 time step

$$i=0, h=-0.25, t_0=1, \theta_0=0.4 \text{ rad/s}, z_0=0 \text{ rad/s}$$

$$K_1^0 = f_2(1, 0.4, 0)$$

$$= 0$$

$$K_2^0 = f_2(1, 0.4, 0)$$

$$= -3.92$$

$$K_2^0 = f_2(1-0.25, 0.4+0, 0+(-3.92 \times -0.25))$$

$$= f_2(0.75, 0.4, 0.98)$$

$$= 0.98$$

$$K_2^2 = f_2(0.75, 0.4, 0.98)$$

$$= -3.92$$

$$\theta_1 = \theta_0 + \left(\frac{1}{2} K_1^0 + \frac{1}{2} K_2^0 \right) h$$

$$= 0.4 + \left(\frac{1}{2} \times 0 + \frac{1}{2} \times 0.98 \right) \times -0.25$$

$$= 0.2775$$

$$z_1 = z_0 + \left(\frac{1}{2} K_1^2 + \frac{1}{2} K_2^2 \right) h$$

$$= 0 + \left(\frac{1}{2} \times -3.92 + \frac{1}{2} \times -3.92 \right) \times -0.25$$

$$= 0.98$$

when,

$$i=1, \quad t_1 = 0.75, \quad h = -0.25, \quad \theta_1 = 0.2775, \quad z_1 = 0.98$$

$$K_1^0 = f_1(0.75, 0.2775, 0.98) \\ = 0.98$$

$$K_1^2 = f_2(0.75, 0.2775, 0.98) \\ = -2.7195$$

$$K_2^0 = f_1(0.5, 0.0325, 1.659875) \\ = 1.659875$$

$$K_2^2 = f_2(0.5, 0.0325, 1.659875) \\ = -0.3185$$

$$\theta_2 = \theta_1 + \left(\frac{1}{2} K_1^0 + \frac{1}{2} K_2^0 \right) h \\ = 0.2775 \left(\frac{1}{2} \times 0.98 + \frac{1}{2} \times 1.659875 \right) \times -0.25 \\ = -0.05248$$

$$z_2 = z_1 + \left(\frac{1}{2} K_1^2 + \frac{1}{2} K_2^2 \right) h \\ = 0.98 + \left(\frac{1}{2} \times -2.7195 + \frac{1}{2} \times -0.3185 \right) \times -0.25 \\ = 1.35975$$

When, $i=2$, $h=-0.25$, $t_2=0.5$, $\theta_2=-0.05248$, $z_2=1.35975$

$$K_1^0 = f_1(0.5, -0.05248, 1.35975)$$

$$= 1.35975$$

$$K_1^2 = f_2(0.5, -0.05248, 1.35975)$$

$$= 0.514304$$

$$K_2^0 = f_1(0.25, -0.3924175, 1.231174)$$

$$= 1.231174$$

$$K_2^2 = f_2(0.25, -0.3924175, 1.231174)$$

$$= 3.8456915$$

$$\theta_3 = \theta_2 + \left(\frac{1}{2} K_1^0 + \frac{1}{2} K_2^0 \right) h$$

$$= -0.05248 + \left(\frac{1}{2} \times 1.35975 + \frac{1}{2} \times 1.231174 \right) \times -0.25$$

$$= -0.37635$$

$$z_3 = z_2 + \left(\frac{1}{2} K_1^2 + \frac{1}{2} K_2^2 \right) h$$

$$= 1.35975 + \left(\frac{1}{2} \times 0.514304 + \frac{1}{2} \times 3.8456915 \right) \times -0.25$$

$$= 0.8147505$$

when,

$$i=3, \quad t_3 = +0.25 \quad h = -0.25, \quad \theta_3 = -0.37635, \quad z_3 = 0.81475$$

$$K_1^0 = f_1(0.25, -0.37635, 0.8147505) \\ = 0.8147505$$

$$K_1^z = f_2(0.25, -0.37635, 0.8147505) \\ = 3.68823$$

$$K_2^0 = f_1(0, -0.580037, -0.107307) \\ = -0.107307$$

$$\theta_4 = \theta_3 + \left(\frac{1}{2} K_1^0 + \frac{1}{2} K_2^0 \right) h \\ = -0.37635 + \left(\frac{1}{2} \times 0.8147505 + \frac{1}{2} \times -0.107307 \right) \times -0.25 \\ = -0.46478$$

b) 2-step $\rightarrow \theta_2 = -0.95975$

4-step $\rightarrow \theta_4 = -0.46478$

$$\text{Relative error} = \frac{\theta_2 - \theta_4}{\theta_4} \\ = \frac{-0.95975 - (-0.46478)}{-0.46478} \times 100 \\ = 106.496\%$$

c) Using,

$$h^* = \left(\frac{t_{ol}}{E_h} \right)^{\frac{1}{p+1}} h$$

where,

$$\frac{t_{ol}}{E_h} = 10^{-3}$$

$$h = 0.5$$

$$p = 2$$

$$\therefore h^* = (10^{-3})^{\frac{1}{3}} \times 0.5$$

$$= 0.05$$

$$\text{So, time step} = \frac{1-0}{0.05} = 20 \text{ steps} //$$

Ans - 2

$$a) \frac{dy}{dx} = y - x^2 + 1$$

$$y(0) = 1$$

$$h = 0.25$$

$$y_1 = y_0 + hf(x_0, y_0) \quad \text{where, } x_0 = 0, y_0 = 1$$

$$y_1 = 1 + 0.25(1 - 0^2 + 1) \\ = 1.5$$

$$y_2 = y_1 + 0.25f(x_1, y_1) \quad \text{where, } x_1 = 0.25, y_1 = 1.5$$

$$y_2 = 1.5 + 0.25f(0.25, 1.5) \\ = 2.109375$$

$$y_3 = y_2 + 0.25f(x_2, y_2) \quad \text{where, } x_2 = 0.5, y_2 = 2.109375$$

$$y_3 = 2.109375 + 0.25f(0.5, 2.109375) \\ = 2.82421875$$

$$y_4 = y_3 + 0.25f(x_3, y_3) \quad \text{where, } x_3 = 0.75, y_3 = 2.82421875$$

$$y_4 = 2.82421875 + 0.25f(0.75, 2.82421875) \\ = 3.639648438 //$$

b) Heun

$$Y_{i+1} = Y_i + \frac{h}{2} (K_1 + K_2)$$

$$\frac{dy}{dx} = y - x^2 + 1$$

$$K_1 = f(x_i, y_i)$$

$$K_2 = f(x_i + h, y_i + hK_1)$$

$$i=0, \quad x_0=0, \quad y_0=1, \quad h=0.25$$

$$K_1 = f_1(x_0, y_0)$$

$$= f_1(0, 1)$$

$$= 2$$

$$K_2 = f_1(x_0 + h, y_0 + K_1 h)$$

$$= f_1(0 + 0.25, 1 + 2 \times 0.25)$$

$$= f_1(0.25, 1.5)$$

$$= 2.4375$$

$$Y_1 = Y_0 + \frac{0.25}{2} (2 + 2.4375)$$

$$= 1 + \frac{0.25}{2} (2 + 2.4375)$$

$$= 1.5547$$

when,

$$x_1 = 0.25 \quad y_1 = 1.5547 \quad h = 0.25$$

$$K_1 = f_1(0.25, 1.5547)$$

$$= 2.4922$$

$$K_2 = f(0.5, 2.17775)$$

$$= 2.92775$$

$$y_2 = y_1 + \frac{h}{2} (K_1 + K_2)$$

$$= 1.5547 + \frac{0.25}{2} (2.4922 + 2.92775)$$

$$= 2.2322$$

when,

$$x_2 = 0.5, \quad y_2 = 2.2322 \quad h = 0.25$$

$$K_1 = f(0.5, 2.2322)$$

$$= 2.9822$$

$$K_2 = f(0.75, 2.97775)$$

$$= 3.41525$$

$$y_3 = y_2 + \frac{h}{2} (K_1 + K_2)$$

$$= 2.2322 + \frac{0.25}{2} (2.9822 + 3.41525)$$

$$= 3.0319$$

when,

$$x_3 = 0.75 \quad y_3 = 3.0319 \quad h = 0.25$$

$$K_1 = f_3(0.75, 3.0319)$$

$$= 3.4694$$

$$K_2 = f_3(0.75 + 0.25, 3.0319 + 3.4694 \times 0.25)$$

$$= f_3(1, 3.89925)$$

$$= 3.89925$$

$$Y_4 = 3.0319 + \frac{0.25}{2} (3.4694 + 3.89925)$$

$$= 3.95298$$

Ans-3

a) Using Taylor series expansion

$$Y_{i+1} = Y_i + h \frac{dy}{dx} + \frac{h^2}{2!} \frac{d^2y}{dx^2}$$

$$\frac{dy}{dx} = \frac{Y_{i+1} - Y_i}{h} - \frac{h}{2!} \frac{d^2y}{dx^2}$$

$$\frac{dy}{dx} = \frac{Y_{i+1} - Y_i}{h} - \tau(h)$$

where, $\tau(h) = O(h)$ is the truncation error.

For the method to be consistent it has to verify

$$\max \tau(h) \rightarrow 0 \text{ when } h \rightarrow 0$$

In our above case, when $h \rightarrow 0$, the $\max \tau(h) \rightarrow 0$,
so, it is consistent.

b) Backward Euler method,

$$Y_i = Y_{i+1} - h \frac{dy}{dx} + O(h^2)$$

$$\frac{dy}{dx} = \frac{Y_{i+1} - Y_i}{h} + \tau(h)$$

$$\therefore Y_{i+1} = Y_i + hf(x_{i+1}, Y_{i+1}) + h\tau_i(h)$$

neglecting the error,

$$Y_{i+1} = Y_i + hf(x_{i+1}, Y_{i+1})$$

c) stability limits for forward Euler method:-

$$\frac{dy}{dx} = -\lambda y$$

$$y_{i+1} = y_i - h\lambda y_i$$

$$y_{i+1} = G y_i \quad \text{with } G = 1 - h\lambda$$

The scheme is stable in $|G| < 1$

$$\therefore |1 - h\lambda| < 1$$

$$h\lambda > 0$$

$$h\lambda < 2$$

$$\boxed{2 > h\lambda > 0}$$

Stability limits for backward Euler method is:-

$$\frac{dy}{dx} = -\lambda y$$

$$y_{i+1} = y_i - h\lambda y_{i+1}$$

$$(1 + h\lambda) y_{i+1} = y_i$$

$$y_{i+1} = G y_i \quad \text{with } G = \frac{1}{1 + h\lambda}$$

scheme is stable is $|1 + h\lambda| > 1$

$$\boxed{h\lambda > 0 \quad h\lambda < -2} \quad \leftarrow \text{unconditionally stable}$$

$$d) \frac{dy}{dx} = -25y^{3.5}$$

$$y(0) = 1 \quad h = \frac{1}{10}$$

when $i=0$,

$$y_{i+1} = y_i + hf(x_{i+1}, y_{i+1})$$

$$y_1 = y_0 + hf(x_1, y_1)$$

$$y_1 = 1 + \frac{1}{10} f(x_1, y_1)$$

$$y_1 = 1 + \frac{1}{10} (-25y_1^{3.5})$$

$$2.5y_1^{3.5} + y_1 - 1 = 0$$

$$f(y) = 2.5y_1^{3.5} + y_1 - 1 = 0$$

$$f'(y) = 8.75y_1^{2.5} + 1$$

Applying newton method with initial guess $(y_1)_0 = 1$

$$(y_1)_1 = (y_1)_0 - \frac{f(y)}{f'(y)}$$

$$= 1 - \frac{2.5}{9.75}$$

$$= 0.74358$$

$$(y_1)_2 = (y_1)_1 - \frac{f(y)}{f'(y)}$$

$$= 0.74358 - \frac{0.629892}{5.1718367}$$

$$= 0.62578$$

when,

$$i=2, \quad Y_1 = 0.62178 \quad h = \frac{1}{10}$$

$$Y_2 = Y_1 + hf(x_2, Y_2)$$

$$Y_2 = 0.62178 + \frac{1}{10} (-2.5Y_2^{3.5})$$

$$Y_2 = 0.62178 - 2.5Y_2^{3.5}$$

$$2.5Y_2^{3.5} + Y_2 - 0.62178 = 0$$

$$f(Y_2) = 2.5Y_2^{3.5} + Y_2 - 0.62178 = 0$$

$$f'(Y_2) = 8.75Y_2^{2.5} + 1$$

Using Newton Method with initial guess $(Y_2)_0 = 0.62178$

$$(Y_2)_1 = (Y_2)_0 - \frac{f(Y_2)}{f'(Y_2)}$$

$$= 0.62178 - \frac{0.47388}{3.66747}$$

$$= 0.49257$$

$$(Y_2)_2 = (Y_2)_1 - \frac{f(Y_2)}{f'(Y_2)}$$

$$= 0.49257 - \frac{0.0804801}{2.48997}$$

$$= 0.4602$$

$$c) \frac{dy}{dx} = -2.5y^{3.5}$$

$$y(0) = 1, \quad x_0 = 0 \quad y_0 = 1 \quad h = \frac{1}{10}$$

$$y_{i+1} = y_i + hf(x_i, y_i)$$

when $i=0$,

$$y_1 = y_0 + hf(x_0, y_0)$$

$$= 1 + \frac{1}{10} f(0, 1)$$

$$= 1 - 2.5$$

$$= -1.5$$

when $i=1$,

$$y_2 = y_1 + hf(x_1, y_1)$$

$$= -1.5 + \frac{1}{10} \left(\frac{1}{10}, -1.5 \right)$$

$$= -1.5 + \frac{1}{10} \left(-2.5 + (-1.5)^{3.5} \right)$$

The solution involves complex number, which is adding up, thus increasing the value of y , which means the solution is unstable.