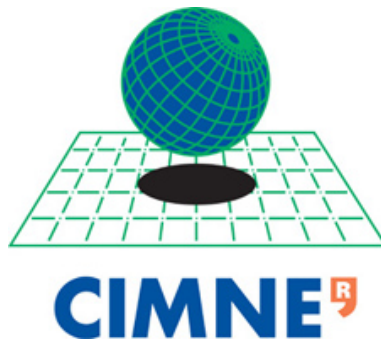

COMPUTATIONAL SOLID MECHANICS

HYPERELASTICITY



BY

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1 Given the stored elastic energy function, Cauchy stress can be calculated as follows:

$$\sigma_{ij} = \frac{\partial W}{\partial \epsilon_{ij}} = \frac{\lambda}{2} \frac{\partial \epsilon_{mm}^2}{\partial \epsilon_{ij}} + \mu \frac{\partial \epsilon_{mn} \epsilon_{mn}}{\partial \epsilon_{ij}} = \lambda \epsilon_{mm} \delta_{mi} \delta_{mj} + 2\mu \delta_{mi} \delta_{nj} \epsilon_{mn} = \lambda \epsilon_{mm} \delta_{ij} + 2\mu \epsilon_{ij}$$

Which can be written in tensorial form as:

$$\boxed{\sigma = \lambda \text{tr}(\epsilon) \mathbf{I} + 2\mu \epsilon}$$

2 The condition of isotropy to be checked is

$$W(\mathbf{F}) = W(\mathbf{FQ})$$

$$W = \frac{\lambda}{2} (\text{tr}(\mathbf{E}))^2 + \mu \text{tr}(\mathbf{E}^2)$$

$$W(\mathbf{F}) = \frac{\lambda}{2} (\text{tr}(\frac{1}{2}(\mathbf{F}^T \mathbf{F} - \mathbf{I})))^2 + \mu \text{tr}((\frac{1}{2}(\mathbf{F}^T \mathbf{F} - \mathbf{I})))^2$$

$$W(\mathbf{FQ}) = \frac{\lambda}{2} (\text{tr}(\frac{1}{2}(\mathbf{Q}^T \mathbf{F}^T \mathbf{F} \mathbf{Q} - \mathbf{I})))^2 + \mu \text{tr}((\frac{1}{2}(\mathbf{Q}^T \mathbf{F}^T \mathbf{F} \mathbf{Q} - \mathbf{I})))^2$$

The used properties to check the condition are $\text{tr}(A+B) = \text{tr}(A) + \text{tr}(B)$, $\text{tr}(\alpha A) = \alpha \text{tr}(A)$, $\text{tr}(AB) = \text{tr}(BA)$, and $QQ^T = I$. Using the first two properties, the condition will be satisfied if the following two equations are true.

$$\text{tr}(\mathbf{F}^T \mathbf{F}) = \text{tr}(\mathbf{Q}^T \mathbf{F}^T \mathbf{F} \mathbf{Q}) \quad \text{tr}(\mathbf{F}^T \mathbf{F} \mathbf{F}^T \mathbf{F}) = \text{tr}(\mathbf{Q}^T \mathbf{F}^T \mathbf{F} \mathbf{Q} \mathbf{Q}^T \mathbf{F}^T \mathbf{F} \mathbf{Q})$$

using the property $\text{tr}(AB) = \text{tr}(BA)$ and $QQ^T = I$, the following is obtained.

$$\text{tr}(\mathbf{Q}^T \mathbf{F}^T \mathbf{F} \mathbf{Q}) = \text{tr}(\mathbf{Q} \mathbf{Q}^T \mathbf{F}^T \mathbf{F}) = \text{tr}(\mathbf{F}^T \mathbf{F})$$

$$\text{tr}(\mathbf{Q}^T \mathbf{F}^T \mathbf{F} \mathbf{Q} \mathbf{Q}^T \mathbf{F}^T \mathbf{F} \mathbf{Q}) = \text{tr}(\mathbf{Q}^T \mathbf{F}^T \mathbf{F} \mathbf{F}^T \mathbf{F} \mathbf{Q}) = \text{tr}(\mathbf{Q} \mathbf{Q}^T \mathbf{F}^T \mathbf{F} \mathbf{F}^T \mathbf{F}) = \text{tr}(\mathbf{F}^T \mathbf{F} \mathbf{F}^T \mathbf{F})$$

The two parts satisfy the condition, therefore, the model is isotropic.

3 Given the stored elastic energy function, the second Piola-Kirchhoff stress can be calculated as follows:

$$S_{ij} = \frac{\partial W}{\partial E_{ij}} = \frac{\lambda}{2} \frac{\partial E_{mm}^2}{\partial E_{ij}} + \mu \frac{\partial E_{mn} E_{mn}}{\partial E_{ij}} = \lambda E_{mm} \delta_{mi} \delta_{mj} + 2\mu \delta_{mi} \delta_{nj} E_{mn} = \lambda E_{mm} \delta_{ij} + 2\mu E_{ij}$$

Which can be written in tensorial form as

$$\boxed{\mathbf{S} = \lambda \text{tr}(\mathbf{E}) \mathbf{I} + 2\mu \mathbf{E}}$$

4 To obtain the nominal stress, first the deformation gradient is calculated

$$\mathbf{F} = \frac{d\mathbf{x}}{d\mathbf{X}} = \begin{bmatrix} \Lambda & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{E} = \frac{1}{2} (\mathbf{F}^T \mathbf{F} - \mathbf{I}) = \frac{1}{2} \begin{bmatrix} \Lambda^2 - 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\mathbf{P} = \mathbf{F}\mathbf{S} = \lambda \text{tr}(\mathbf{E})\mathbf{F} + 2\mu \mathbf{F}\mathbf{E} = \frac{1}{2} \lambda (\Lambda^2 - 1) \begin{bmatrix} \Lambda & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} + \mu \begin{bmatrix} \Lambda^3 - \Lambda & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$P_{xX} = (\frac{\lambda}{2} + \mu)(\Lambda^3 - \Lambda)$$

The curve is plotted using $\mu = 77$ and $\lambda = 115$.

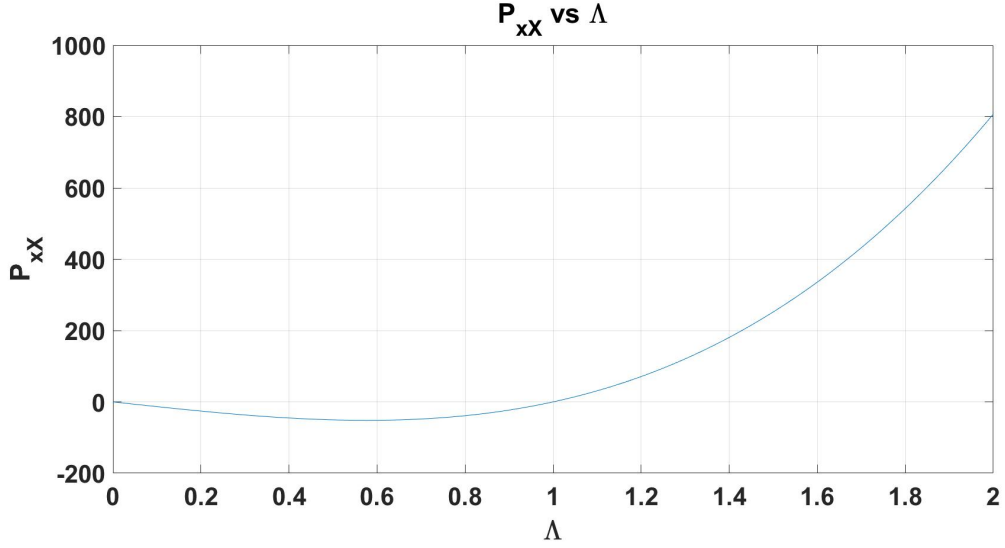


Figure 1: P_{xX} vs Λ

5 The relationship is not monotonic if the slope of the curve is zero at some point.

$$\frac{\partial P_{xX}}{\partial \Lambda} = \left(\frac{\lambda}{2} + \mu\right)(3\Lambda^2 - 1)$$

The derivative can be zero which means that the relationship is not monotonic.

$$\Lambda_{cr} = \sqrt{\frac{1}{3}}$$

This value doesn't depend on the elastic constants.

To check the growth condition, the Jacobin and the stored energy are calculated.

$$J = \det(\mathbf{F}) = \Lambda$$

$$W = \frac{\lambda}{2}(\text{tr}(\mathbf{E}))^2 + \mu \text{tr}(\mathbf{E}^2) = \frac{\lambda}{8}(\Lambda^2 - 1)^2 + \frac{\mu}{4}(\Lambda^2 - 1)^2 = \left(\frac{\lambda}{8} + \frac{\mu}{4}\right)(\Lambda^2 - 1)^2$$

$$\lim_{\Lambda \rightarrow 0^+} W = \lim_{\Lambda \rightarrow 0^+} \left(\frac{\lambda}{8} + \frac{\mu}{4}\right)(\Lambda^2 - 1)^2 = \left(\frac{\lambda}{8} + \frac{\mu}{4}\right) \neq \infty$$

From the obtained results, it is conclude that Kirchhoff Saint-Venant material model fails after a certain compression level. If the material is compressed from its undeformed configuration, stress will increase to resist the deformation. However, when the stretch ratio reaches 0.577, the stress reaches a maximum. Further compression will lead to decrease in stress till it becomes zero when J is equal to zero.

6 To check if the new model circumvent the drawbacks of the previous model, the nominal stress is first calculated.

$$\mathbf{P} = \frac{\partial W}{\partial \mathbf{F}} = \mathbf{F} \frac{\partial W}{\partial \mathbf{E}} = \lambda \ln J \mathbf{J} \mathbf{F}^{-T} + 2\mu \mathbf{F} \mathbf{E}$$

$$P_{xX} = \lambda \ln \Lambda + \mu(\Lambda^3 - \Lambda)$$

$$\frac{\partial P_{xX}}{\partial \Lambda} = \frac{\lambda}{\Lambda} + \mu(3\Lambda^2 - 1)$$

The obtained derivative can be zero depending on the elastic constants.

$$\lim_{\Lambda \rightarrow 0^+} W = \lim_{\Lambda \rightarrow 0^+} \frac{\lambda}{2} (\ln \Lambda)^2 + \mu(\Lambda^2 - 1)^2 = \infty \quad \text{only if } \lambda > 0$$

It is concluded that the modified material model circumvents the drawbacks of the previous model only with a good choice of the elastic constants.