

$$1. \begin{bmatrix} u \\ w \end{bmatrix} = \begin{bmatrix} N_1 & 0 & N_2 & 0 & N_3 & 0 \\ 0 & N_1 & 0 & N_2 & 0 & N_3 \end{bmatrix} \begin{bmatrix} u \\ w \end{bmatrix} = \tilde{N} \tilde{u}$$

$$\tilde{u} = \begin{bmatrix} u_1 \\ w_1 \\ u_2 \\ w_2 \\ u_3 \\ w_3 \end{bmatrix}; \quad e = \begin{bmatrix} e_{rr} \\ e_{\theta\theta} \\ e_{zz} \\ 2e_{rz} \end{bmatrix} = \tilde{B} \tilde{u};$$

$$\tilde{B}_i = \begin{bmatrix} \frac{\partial N_i}{\partial r} & 0 \\ \frac{N_i}{r} & 0 \\ 0 & \frac{\partial N_i}{\partial z} \\ \frac{\partial N_i}{\partial z} & \frac{\partial N_i}{\partial r} \end{bmatrix};$$

We choose the shape function like below:

( $i=1, 2, 3$ )

$$N_i = \frac{1}{2A} (a_i + b_i r + c_i z);$$

$$\textcircled{1} \begin{cases} a_1 = r_2 z_3 - r_3 z_2 = ab \\ b_1 = z_2 - z_3 = -b \\ c_1 = 0 \end{cases}$$

$$\textcircled{2} \begin{cases} a_2 = r_3 z_1 - r_1 z_3 = 0 \\ b_2 = z_3 - z_1 = b \\ c_2 = r_1 - r_3 = -a \end{cases}$$

$$\textcircled{3} \begin{cases} a_3 = r_1 z_2 - r_2 z_1 = 0 \\ b_3 = z_1 - z_2 = 0 \\ c_3 = r_2 - r_1 = a \end{cases}$$



So we get:

$$\underline{B}_r = \frac{1}{2A} \begin{bmatrix} b_1 & 0 & | & b_2 & 0 & | & b_3 & 0 \\ f_1 & 0 & | & f_2 & 0 & | & f_3 & 0 \\ 0 & c_1 & | & 0 & c_2 & | & 0 & c_3 \\ \hline c_1 & b_1 & | & c_2 & b_2 & | & c_3 & b_3 \end{bmatrix}; \begin{cases} f_1 = \frac{a_1 + b_1 r + c_1 z}{r} = \frac{ab - br}{r} \\ f_2 = \frac{br - az}{r} \\ f_3 = a \frac{z}{r} \end{cases}$$

$$\Rightarrow \underline{B}_r^T \underline{E} \underline{B}_r = \frac{1}{4A^2} \begin{bmatrix} b^2 + f_1^2 & 0 & -b^2 + f_1 f_2 & 0 & f_1 f_3 & 0 \\ 0 & b^2/2 & ab/2 & -b^2/2 & -ab/2 & 0 \\ -b^2 + f_1 f_2 & ab/2 & b^2 + f_2^2 + a^2/2 & -ab/2 & f_2 f_3 - a^2/2 & 0 \\ 0 & -b^2/2 & -ab/2 & a^2 + b^2/2 & ab/2 & -a^2 \\ f_1 f_3 & -ab/2 & f_2 f_3 - a^2/2 & ab/2 & f_3^2 + a^2/2 & 0 \\ 0 & 0 & 0 & -a^2 & 0 & a^2 \end{bmatrix} \quad (\text{This matrix is symmetric})$$

$$\Rightarrow K^e = \iiint \underline{B}_r^T \underline{E} \underline{B}_r r dr dz$$

$$= \begin{bmatrix} \frac{2}{3}b & 0 & -b/4 & 0 & b/12 & 0 \\ b/6 & a/6 & -b/6 & a/6 & 0 & 0 \\ 4a^2/9 + a^2/6b & -a/6 & b/8 - a^2/6b & 0 & 0 & 0 \\ a^2/3b + b/6 & a/6 & -a^2/3b & 0 & 0 & 0 \\ b/9 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & a^2/3b \end{bmatrix}$$

Symmetry



We can find that the 2, 4, 6 rows and columns' sum is zero. But the 1, 3, 5 rows and columns don't follow this.

## Reason

① for rows 2, 4, 6.

$\vec{f}^e = \vec{K}^e \vec{u}^e$ ; the sum of 2, 4, 6 rows is zero. this situation

can only happen when  $u_1^e = u_2^e = u_3^e = w_1^e = w_2^e = w_3^e$ , which means that the

element only has rigid motion. The element is actually in 3-D, r-direction

not 2-D like simplified. So the ~~rigid~~ motion means that the

element has extended on r-direction. So it needs forces on r

direction. This is the reason why 1, 3, 5 rows' sum is not

zero. But on z-direction, the situation is different, the

element only has rigid displacement which doesn't need force

and the  $f_{z1} = f_{z2} = f_{z3} = 0$  under this condition. so the sum

of 2, 4, 6 becomes zero.

② for columns 2, 4, 6

Because the  $\vec{K}^e$  matrix is symmetric, so the ~~columns~~ 2,

4, 6 columns' sum is also zero.



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$$\underline{f}_z^e = \iiint \underline{N}^T \underline{b} \cdot r \cdot dr dz ; \quad \underline{b} = [0, -g]^T$$

$$= \iiint \begin{bmatrix} 0 \\ -N_1 g \\ 0 \\ -N_2 g \\ 0 \\ -N_3 g \end{bmatrix} \cdot r \cdot dr dz$$

$$= ab \begin{bmatrix} 0 \\ a/4 - ab/3 \\ 0 \\ -a/8 \\ 0 \\ -a/8 \end{bmatrix}$$