

FINAL EXAM

Problem 1:

Consider:

$$\begin{cases} u_t + a u_x - \nu u_{xx} = 0 & x \in (0,1), t > 0 \\ u(x,0) = u_0(x) & x \in (0,1) \\ u_x(0) = u_x(1) = 0 \end{cases}$$

① Discretize the BVP in time using Lax-Wendroff.

Since it is not possible to design one-stage schemes more than second order accurate schemes for convection-diffusion problems (due to C^0 and 2nd derivatives incompatibility) a two-stage scheme is proposed.

Lax-Wendroff \equiv Explicit Padé scheme $R_{2,0}$

using the approximation:

$$u(t^{n+1}) = u(t^n) + \Delta t \left. \frac{\partial}{\partial t} \left(u + \frac{\Delta t}{2} \frac{\partial u}{\partial t} \right) \right|_{t=t^n} + O(\Delta t^3)$$

and the 2 stages:

$$\begin{aligned} u^{n+1/2} &= u^n + \frac{1}{2} \Delta t u_t^n \\ u^{n+1} &= u^n + \Delta t u_t^{n+1/2} \end{aligned}$$

② Weak-form:

let us write one stage discretization

$$\frac{u^{n+\alpha} - u^n}{\alpha \Delta t} = u_t^{n+\beta} = -a \nabla u^{n+\beta} + \nu \nabla^2 u^{n+\beta}$$

and then multiply each term by $w \in H_0^1(\Omega)$ test function and operating, we get the weak form associated:

$$\left(\frac{u^{n+\alpha} - u^n}{\alpha \Delta t}, w \right) + a(u^{n+\beta}, w) = 0.$$

where a :

$$a(u^{n+\beta}, w) = (a \cdot \nabla u^{n+\beta}, \nabla w) + (\nabla \cdot \nabla u^{n+\beta}, w).$$

③ Discretize in space using Galerkin finite element method.

The spaces used to solve the weak form are

$$S_t := \{ u \mid u(\cdot, t) \in H^1(\Omega), t \in [0, T] \text{ and } u(x, t) = u_D \text{ for } x \in \Gamma_D \}$$

+

the space of weighting functions:

$$V := \{ w \in H^1(\Omega) \}$$

if we want to use the Galerkin discretization we must define S^h and V^h such that:

$$S_t^h := \{ u \mid u(\cdot, t) \in H^1(\Omega), u(\cdot, t)|_{\Omega^e} \in \mathcal{P}_p(\Omega^e) \forall e \text{ and } u = u_D \text{ on } \Gamma_D \}$$

$$V^h := \{ w \in H^1(\Omega) \mid w|_{\Omega^e} \in \mathcal{P}_p^{\neq}(\Omega^e) \forall e \text{ and } w = 0 \text{ on } \Gamma_D \}$$

$$\begin{cases} \left(\frac{u^{h,n+\alpha} - u^{h,n}}{\alpha \Delta t}, w^h \right) + a(u^{h,n+\beta}, w^h) = 0 \\ (w^h, u^h(x, 0)) = (w^h, u_D(x)) \end{cases}$$

with:

$$u^h(x, t) = \sum_{i \in \mathcal{N}_D} N_i^{\alpha}(t) u_i + \sum_{i \in \mathcal{N}_D} N_i(x) \cdot u_D(x, t).$$

with the discrete form.

$$M u_t + (C + K) u = 0$$

with M, C and K of the form:

$$M_{ij}^e = \int_{\Omega^e} N_i N_j d\Omega$$

$$C_{ij}^e = \int_{\Omega^e} N_i (a \cdot \nabla N_j) d\Omega$$

$$K_{ij}^e = \int_{\Omega^e} \nabla N_i \cdot (v \nabla N_j) d\Omega$$

- ④ Solutions for (a, v_i) with $(a, v_i) = (1; 0, 0, 0, 0, 1)$, $h = 0.1$ and $\Delta t = (0.1; 0.05; 0.1)$ presents numerical oscillations on the solution. Why?

The numerical oscillations are due to methods like the one derived, Galerkin+explicit Padé, are conditionally stable.

If a Fourier analysis is done and the amplification factor calculated, it is of the form:

$$G(\xi, C, d, C, r) = R_{\text{img}, 0}(z) \text{ with } z := \frac{K(\xi d) A(\xi, C) - rM(\xi)}{M(\xi)}$$

and the Courant and Peclet number will play a major role on its stability.

It can be seen that since the convection ~~is~~ parameter dominates over the diffusion Galerkin formulation lacks sufficient spatial stability when boundary layers appears.



A. Explain to your friend how you found the sum of the series $\sum_{n=1}^{\infty} \frac{1}{n^2}$. (10 points)

My friend said that the sum of the series is $\frac{\pi^2}{6}$. I said that the sum of the series is $\frac{\pi^2}{6}$. I said that the sum of the series is $\frac{\pi^2}{6}$.

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Problem 2:

Consider the Stokes problem:

$$\begin{cases} -\nu \nabla^2 u + \nabla p = b & \text{in } \Omega \\ \nabla \cdot v = 0 & \text{in } \Omega \\ v = 0 & \text{on } \partial\Omega. \end{cases}$$

① Derive the weak form. Detail the steps.

To ~~derive~~^{derive} the weak form, we firstly need to define the next spaces:

▣ Trial solution space:

$$S := \{ v \in H^1(\Omega) \mid v = v_0 \text{ on } \Gamma_D \}$$

▣ Weighting functions of the velocity, w .

$$V := \{ w \in H^1(\Omega) \mid w = 0 \text{ on } \Gamma_D \}$$

▣ Space for the pressure.

$$Q = L_2(\Omega)$$

Also let us define the boundary tractions in order to have a well posed BVP:

$$-pn + \nu (n \cdot \nabla)v = t \quad \text{on } \Gamma_N \quad (\text{Neumann b.c.})$$

also called "pseudo-traction"

So applying the divergence theorem to the pressure gradient term and to the viscous term, the weak form reads:

find $(v, p) \in S \times Q$ such that

$$a(w, v) + b(w, p) + b(v, q) = (w, b) + (w, t)_{\Gamma_N} \quad \forall (w, q) \in V \times Q$$

with

$$a(w, v) = \int_{\Omega} \nabla w : \nu \nabla v \, d\Omega.$$

since $v_0 = 0$ (Dirichlet BC)

② Discretize the problem using Galerkin finite element approximation

we need to introduce approximations for velocity and pressure:

$$v_i^h \in \mathcal{S}^h$$

$$p^h \in \mathcal{Q}^h$$

and weighting function:

$$w^h \in \mathcal{V}^h.$$

and then:

$$a(w^h, v^h) + b(w^h, p^h) = (w^h, b^h) + (w^h, t^h)_{\Gamma_N}, \quad b(u^h, q^h) = 0$$

with $v = 0$ on $\partial\Omega$ and:

$$u_i^h = \sum_{A \in \mathcal{T}_h} N_i(x) u_i$$

$$p^h(x) = \sum_{\hat{A} \in \hat{\mathcal{T}}_h} \hat{N}_i(x) p_i$$

~~or~~

with matrix form of the problem:

$$\begin{bmatrix} K & G \\ G^T & 0 \end{bmatrix} \begin{bmatrix} u \\ p \end{bmatrix} = \begin{bmatrix} F \\ 0 \end{bmatrix}$$

with

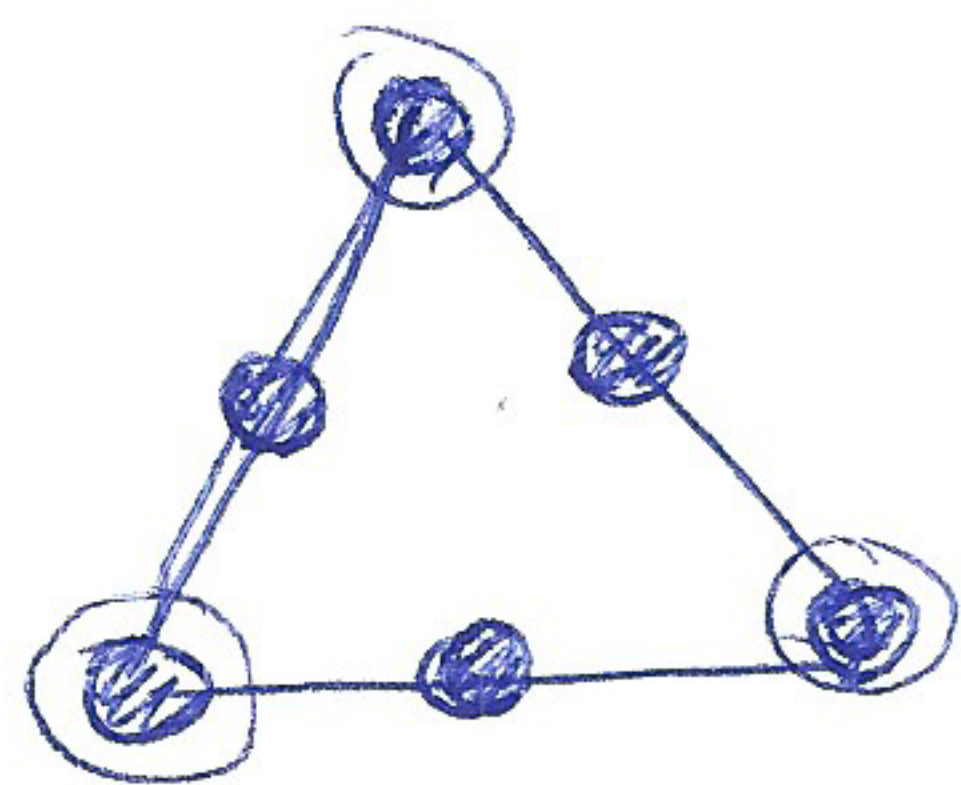
K	$a(w, u)$	$\int \nabla w : \nu \nabla v \, d\Omega.$
G	$b(w, p)$	$-\int p \nabla w \, d\Omega.$
F	$(w, b) + (w, t)_{\Gamma_N}$	$\int w b \, d\Omega + \int_{\Gamma_N} w t \, d\Omega.$
G^T	$b(u, q)$	$-\int q \nabla u \, d\Omega.$

③ Discuss whether the problem can be solved using P_1/P_1 and P_2/P_1 elements.

In order to know if the pairs proposed are appropriate to solve the problem, they must fulfill the inf-sup condition. The inf-sup condition states that the velocity and pressure spaces have to be linked, so the pair chosen have to fulfill:

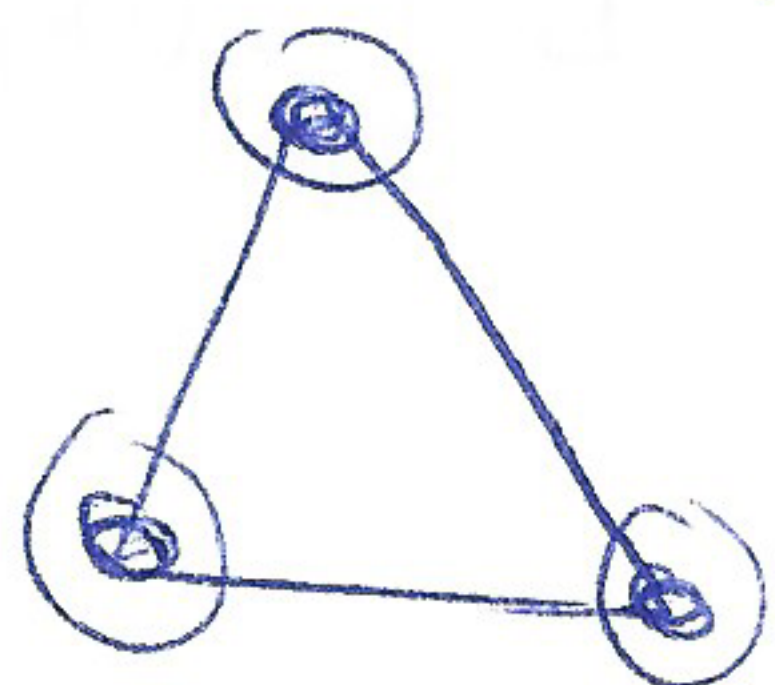
$$\inf_{q^h \in Q^h} \sup_{w^h \in W^h} \frac{(q^h, \nabla w^h)}{\|q^h\|_0 \|w^h\|_1} \geq \alpha > 0$$

This condition is fulfilled for the pair P_2/P_1 (Quadratic velocity / linear pressure)



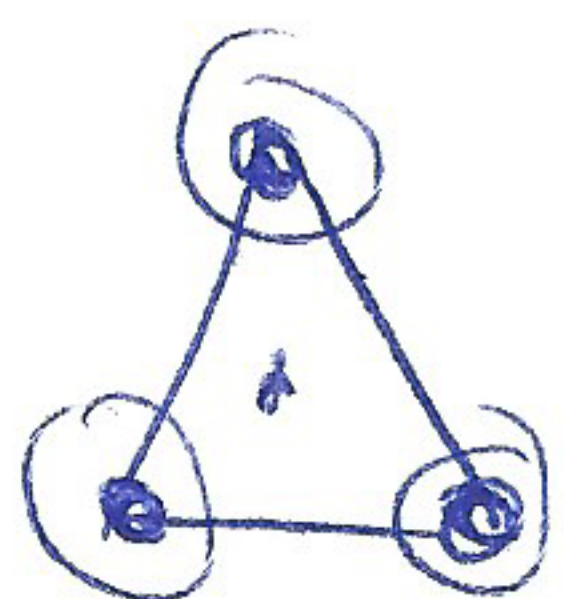
○ pressure
● velocity

Whereas the P_1/P_1 method will not fulfill this condition, and won't give proper results.



○ pressure
● velocity

This element can be improved using bubble functions in the velocity nodes and then fulfill the inf-sup condition:



P_1^+ / P_1

○ pressure
● velocity
⊗ Bubble.

④ Derive a stabilized GLS for the Stokes formulation. Use linear elements for both velocity and pressure to derive the stabilized GLS for Stokes problem lets ~~us~~ write the problem in the variational form.

$$a(w, v) + b(w, p) + b(v, q) = (w, b) \quad , \quad \forall (w, q) \in V \times Q$$

and define: the square of the residual of the momentum eq:

$$L_S(v, p) := (-\nu \nabla^2 v + \nabla p - b, -\nu \nabla^2 v + \nabla p - b)$$

stationary condition L_S implies:

$$\left. \frac{dL_S(v + \epsilon w, p + \epsilon q)}{d\epsilon} \right|_{\epsilon=0} = 0$$

that implies:

$$\begin{cases} (-\nu \nabla^2 w, -\nu \nabla^2 v + \nabla p - b) = 0 & \forall w \in V \\ (\nabla q, -\nu \nabla^2 v + \nabla p - b) = 0 & \forall q \in Q \end{cases}$$

the stabilized discrete problem (using the Galerkin interpolation) is now:

$$\begin{cases} a(w^h, v^h) + b(w^h, p^h) + \sum_{e=1}^{nel} \tau_e (-\nu \nabla^2 w^h, -\nu \nabla^2 v^h + \nabla p^h - b^h)_{\Omega_e} = (w^h, b^h) + (w^h, t^h)_{\Gamma_N} \\ b(v^h, q^h) - \sum_{e=1}^{nel} \tau_e (\nabla q^h, -\nu \nabla^2 v^h + \nabla p^h - b^h)_{\Omega_e} = 0 \end{cases}$$

with τ_e stabilization parameter of the form:

$$\tau_e = \alpha_0 \frac{h_e^2}{\nu}$$

For linear elements: $\nabla^2 = 0$ and $\alpha_0 = 1/3$

$$\begin{cases} a(w^h, v^h) + b(w^h, p^h) = (w^h, b^h) + (w^h, t^h)_{\Gamma_N} \\ b(v^h, q^h) - \sum_{e=1}^{nel} \tau_e (\nabla q^h, \nabla p^h) + \sum_{e=1}^{nel} \tau_e (\nabla q^h, b^h)_{\Omega_e} \end{cases}$$

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Problem 3:

① Consider 1D steady-state convection diffusion problem:

$$\begin{cases} u_x - \nu u_{xx} = f(x) & \text{for } 0 < x < 1 \\ u(0) = u(1) = 0 \end{cases}$$

We consider $\nu = 1$ and $\nu = 10^{-2}$

a). How the Galerkin method will behave if a mesh of 10 uniform linear elements is used to approximate the exact solution

1. First we multiply the terms in the strong form by test function $w \in V$, $V := \{w \in H^1(\Omega) \mid w=0 \text{ on } \Gamma_0\}$ and integrate by parts:

$$\int_0^1 (w u_x + w_x \nu u_x) dx = \int_0^1 w f(x) dx$$

2. Discretize the weak form: $h = 0.1$ ($n_{el} = 10$ / $h = \frac{L}{n_{el}} = \frac{1}{10}$)

$$\int_0^1 \sum (N_i \frac{\partial N_j}{\partial x} + \nu \frac{\partial N_i}{\partial x} \frac{\partial N_j}{\partial x}) u dx = \int_0^1 N_i f(x) dx$$

3. In matrix form, matrices are:

$$C^e = \int_{\Omega} \begin{pmatrix} N_1 \frac{\partial N_1}{\partial x} & N_1 \frac{\partial N_2}{\partial x} \\ N_2 \frac{\partial N_1}{\partial x} & N_2 \frac{\partial N_2}{\partial x} \end{pmatrix} dx = \frac{1}{2} \begin{pmatrix} -1 & +1 \\ -1 & +1 \end{pmatrix}$$

$$K^e = \nu \int_{\Omega} \begin{pmatrix} \frac{\partial N_1}{\partial x} \frac{\partial N_1}{\partial x} & \frac{\partial N_1}{\partial x} \frac{\partial N_2}{\partial x} \\ \frac{\partial N_2}{\partial x} \frac{\partial N_1}{\partial x} & \frac{\partial N_2}{\partial x} \frac{\partial N_2}{\partial x} \end{pmatrix} dx = \frac{\nu}{0.1} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$$

with $N_1(\xi) = \frac{1}{2}(1-\xi)$, $N_2(\xi) = \frac{1}{2}(1+\xi)$

4. Galerkin equation at an interior node j :

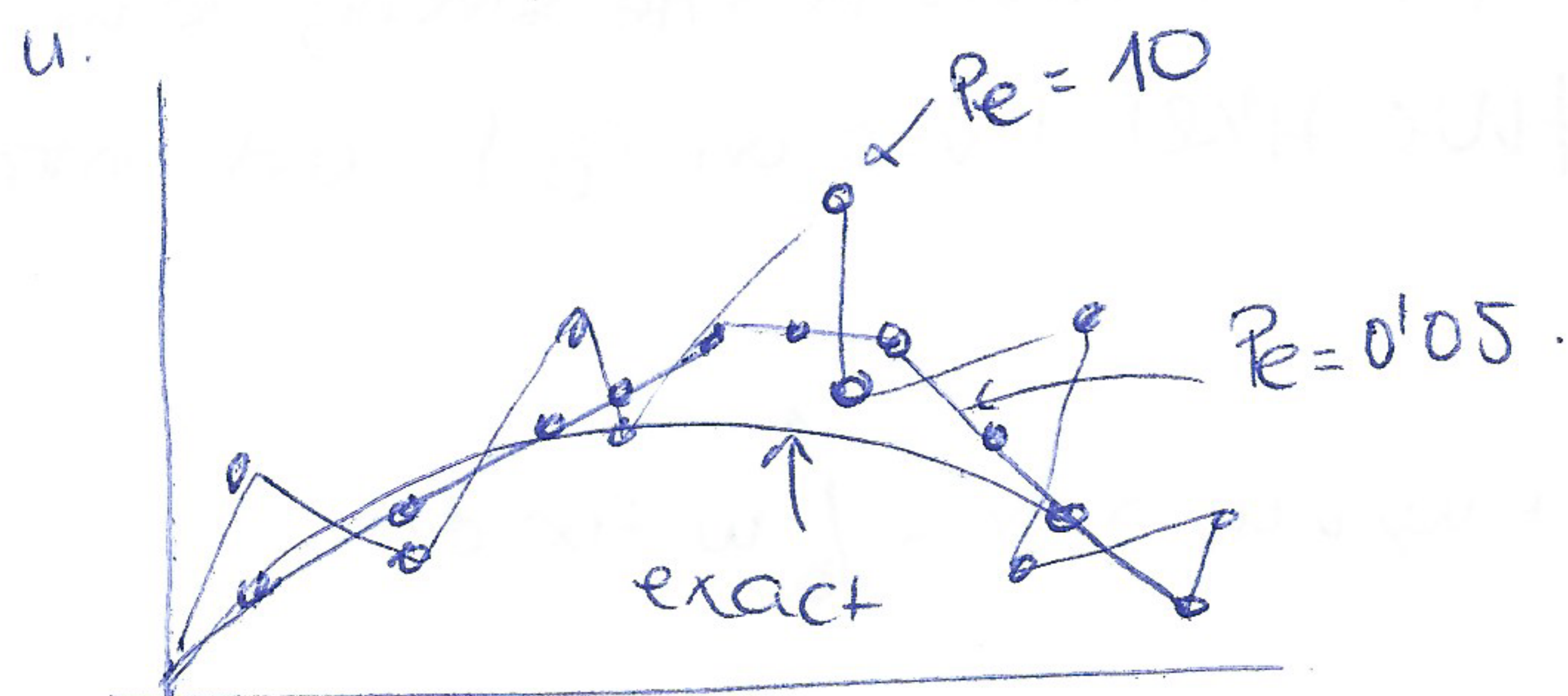
$$\left(\frac{u_{j+1} - u_{j-1}}{0.2} \right) - \nu \left(\frac{u_{j+1} - 2u_j + u_{j-1}}{(0.1)^2} \right) = \text{RHS}$$

5. If we introduce the Péclet number $Pe = \frac{ah}{2\nu}$.

$$\frac{1}{0.2} \left(\frac{Pe-1}{Pe} u_{j+1} + \frac{2}{Pe} u_j - \frac{Pe+1}{Pe} u_{j-1} \right) = \text{RHS}$$

It can be observed that for $Pe > 1$ we will obtain node-to-node oscillations in the solution. For the parameters in the problem.

$\nu = 1.$	$\nu = 0,01.$
$Pe = \frac{0,1}{2} = 0,05$	$Pe = \frac{0,1}{0,01} = 10.$



b) GLS method. τ ?

1. let's define the operator. $\underbrace{0 \text{ to L.F.F}}_{\text{SUPG}}$

$$P(w) = L(w) = \underbrace{a \nabla w}_{\text{SUPG}} - \nabla (\nu \nabla w) + \underbrace{\sigma w}_{\text{Galerkin}}$$

2. weak form GLS:

$$a(w^h, u^h) + c(a; w^h, u^h) + \sum_e \int_{\Omega^e} L(w^h) \tau [L(u^h) - f(x)] d\Omega + \sigma w = (w^h, f) + (w^h, h)_{\Gamma}$$

3. τ ? For linear elements according to the slides.

$$\tau = \frac{h}{2a} \left(\coth(\beta) - \frac{1}{\beta} \right)$$

Since it is consistent and symmetric will improve the results, but it still 'carries' the Galerkin instabilities:

with σ -w. For Linear Finite Elements we will get the same result as for SUPG but the Galerkin term weighted $1 + \sigma \tau$ times.

② consider a 1D pure convection equation:

$$u_t + au_x = 0 \quad \text{for } 0 < x < 1, \quad t > 0$$

$$u(x, 0) = f(x) \quad \text{for } 0 < x < 1.$$

a) comment on the results.

we can see that for LW and CN with a Courant number equals to 0.5 the results are very similar for both methods.

But when $Cu = 0.9$, while CN keeps providing a good approximation LW becomes unstable.

If a Fourier analysis for stability is done, the amplification factors for both methods are:

$$|G_{CN}| = 1.$$

$$|G_{LW}| = \left| \frac{1 - \left(\frac{2}{3} + 2C^2\right) \sin^2 \frac{\xi}{2} - iC \sin \xi}{1 - \frac{2}{3} \sin^2 \frac{\xi}{2}} \right|$$

So, CN is unconditionally stable whereas LW is not, its stability will depend on the Courant number. Actually it will be stable for $C < 0.57$

b). it is better to solve the problem using LW with a lumped mass matrix?

If a diagonal mass matrix is used, the amplification factor for LW will be:

$$G_{LW_{LM}} = 1 - 2C^2 \sin^2 \frac{\xi}{2} + C \sin \xi$$

which is stable up to $C^2 \leq 1$.

So with the $C = 0.9$, we will still have a stable solution.

③ Picard and Newton-Raphson methods on Navier-Stokes

Regarding the solution for $Re = 100$, we see that both methods behave, and converge, as expected, that is, linearly for Picard and quadratic for N-R.

When increasing the Reynolds number to $Re = 1000$ we see that Picard methods continue converging linearly ~~linearly~~ while N-R does not converge.

④ Advantages HDG

Due to the hybridization it is capable to reduce significantly the Dofs and get faster results (in time), faster convergence ~~speed~~ for small degree polynomials.